

Where were we? Ah right, chopping plane graph into pieces.

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Dense-distance graphs.

Recall a good r-division: n-vertex plane graph G.

- Chop G into $O(n/r)$ pieces
- each piece has size $\leq r$.
- #bdry vertices per piece is $O(\sqrt{nr})$
- #holes per piece is $O(1)$

Imagine we use MSSP to compute APSP between bdry vertices for each piece.

Now, replace each piece w/ a complete graph on bdry vertices.

• Obtaining dists: $\left[\begin{matrix} O(r \log r) \\ + O(\sqrt{nr})^2 \cdot O(\log r) \end{matrix} \right] \cdot O(\frac{n}{r}) = O(n \log n)$

• #vertices in the new graph (dense-dist. graph):

$O(\frac{n}{r}) \cdot O(\sqrt{nr})^2 = O(n \sqrt{nr}) = O(n^2)$

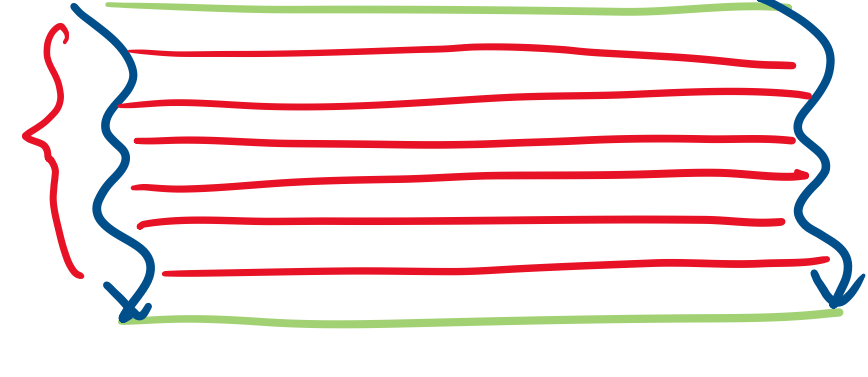
example. Shortest path on planar graphs w/ ≥ 0 edge weights

1. Declare s & t as "bdry vertices".
 2. Build r-division. (Choose r later) $O(n)$
 3. Build DDG. $O(n \log r)$
 4. Dijkstra from s. $O(V \log V + E) = O(\frac{n}{r} \log n + n)$
- If we set $r = \log^2 n$, $O(n \log \log n)$ in total!

Okay, but what do we need?

$O(n \log \log n)$ preprocessing.

$O(n)$ $\approx \sqrt{nr}$ parallel shortest paths.



$T(n, \pi) \leq O(n \log \log n) + \sum_{i=1}^{\pi/poly \log \pi} T(n_i, poly \log \pi) \Rightarrow O(n \log \log n)$

Can't afford $O(\frac{n}{r} \log n + n) = O(\log \frac{n}{poly \log \pi})$.

Main Question: How do we perform Dijkstra w/o checking edges?

FR-Dijkstra. [Fakcharoenphol - Rao '01]

What do we need for Dijkstra: **algorithms!**

- FINDMIN: Return min-element from a heap.

What are the elements?

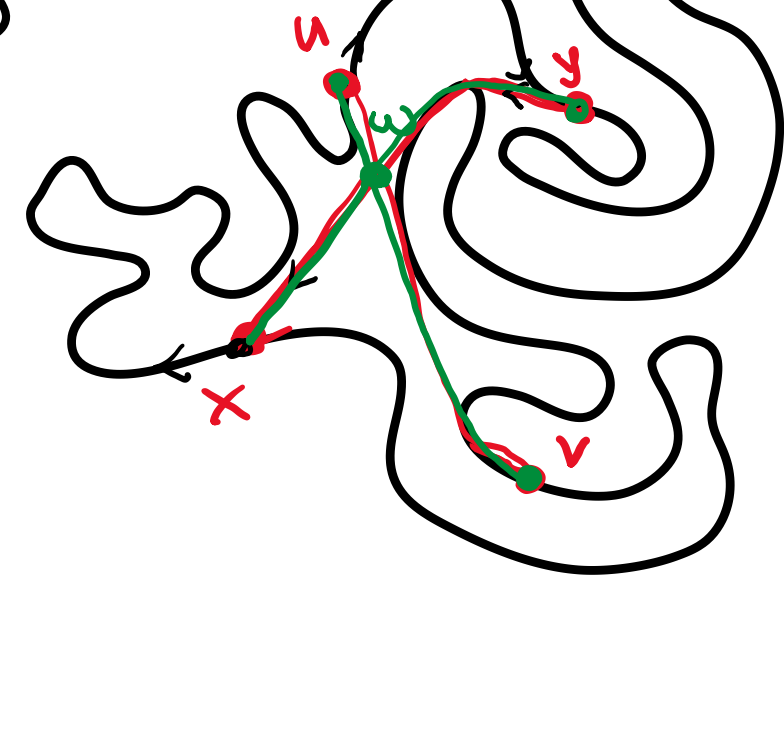
The edges in DDG of a piece.

We can't build the whole heap!

\Rightarrow Explore properties of the distance matrix.

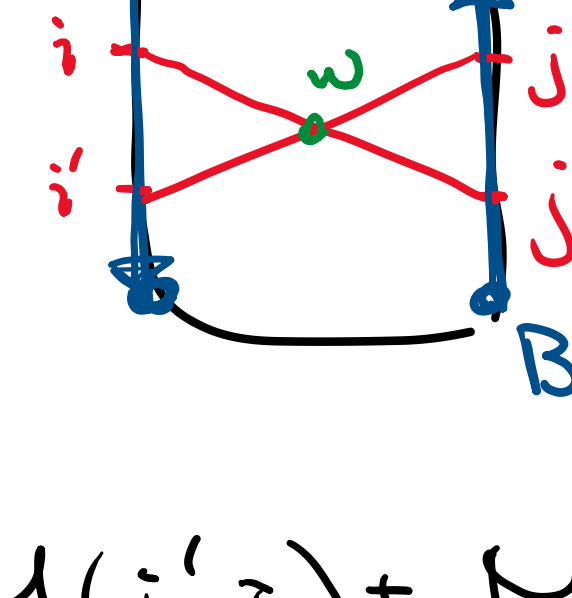
Monge property. [Monge 1981] (Another close friend of JCT).

$d(u,v) + d(x,y) \geq d(u,x) + d(v,y)$



Monge matrix.

A	10	17	13	28	23
	17	22	16	29	23
i	24	28	22	34	24
i'	11	13	6	17	7
	45	44	32	37	23
	36	33	19	21	6
B	75	66	51	53	34



$M(i,j) + M(i',j') \geq M(i',j) + M(i,j')$ $\forall i \leq i', j \leq j'$

$M(i',j') - M(i',j) \geq M(i',j) - M(i,j)$

- Row-differences are growing monotonically.

SMWK algorithm. [AKMSW'87] [KK'90]

Row-wise minimums can be found in $O(n)$ time for $n \times n$ Monge matrix.

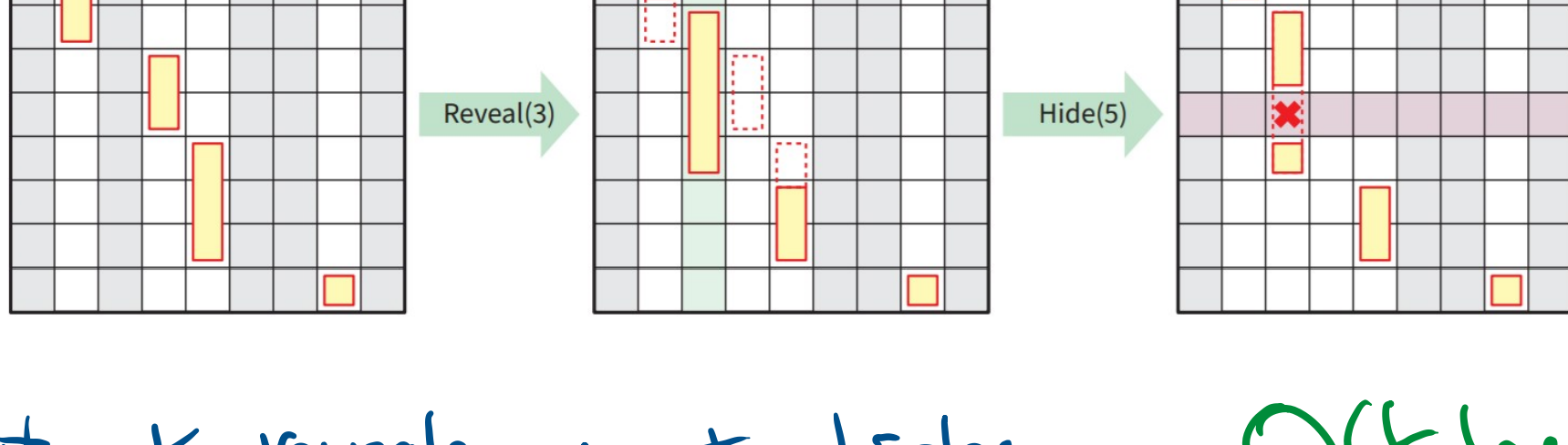
Monge Heap.

Let's say we have a Monge matrix M.

Some entries are hidden, and some visible.

Monge heap supports:

- FINDMIN: smallest element **visible** in M.
- REVEAL(j, x) reveal j-th column w/ additive x
- HIDE(i): hide i-th row.



data structure!

At most k reveals & k hides. $O(k \log k)$

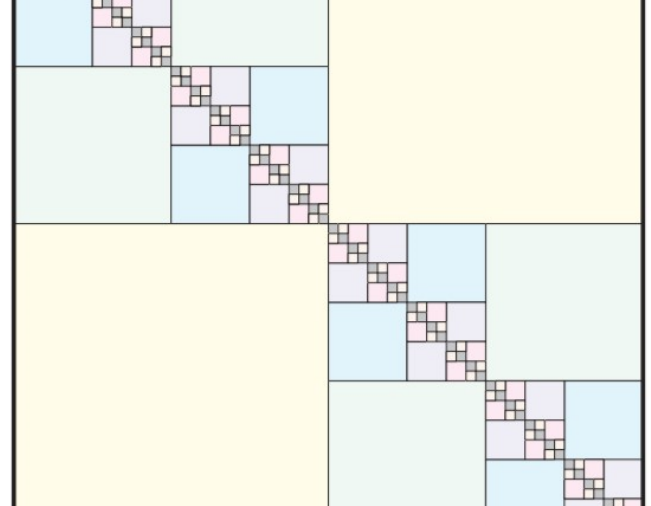
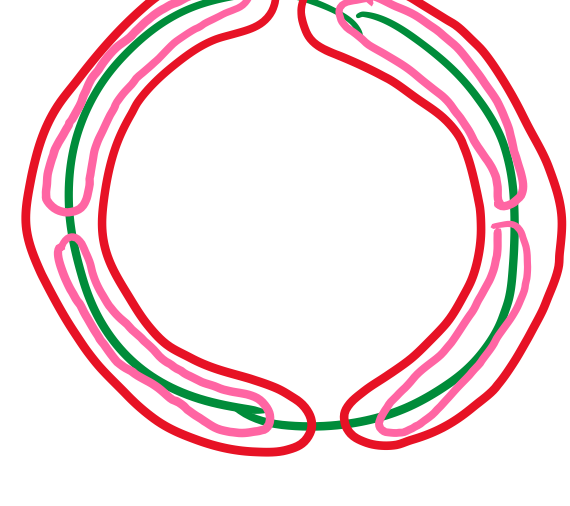
(Priority queue + binary tree + range-min queries.)

Decompose a piece into Monge matrices.

Let D be the distance matrix of a piece. (w/ \sqrt{nr} bdry vertices)

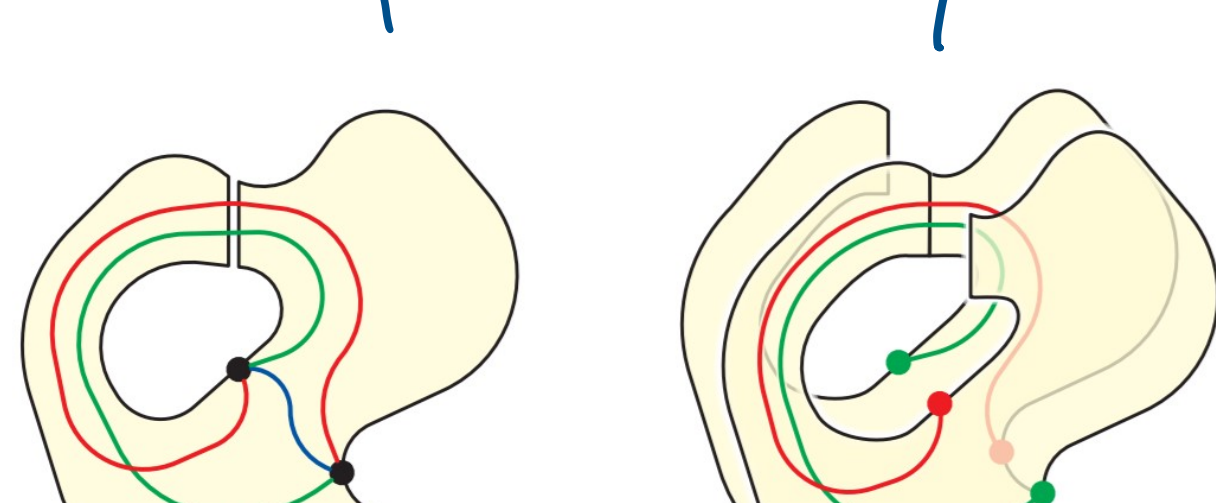
D can be decomposed into $O(\log r)$ levels of Monge matrices:

1. For a single hole, divide-x-conquer.



#Monge matrices:
 $\#M(k) = 2 + 2 \cdot \#M(\frac{k}{2}) \leq 3k - 2$
 Total Parameters:
 $TP(k) = 2 \cdot \frac{k}{2} + 2 \cdot TP(\frac{k}{2}) \leq O(k \log k)$

2. For multiple hole, cyclic covering.



$O(1)^2$ pairs of holes:
 \Rightarrow min of $O(1)$ Monge matrices.

Maintaining a ^{piece} heap of min-elements in all Monge heaps, one per Monge matrix.

FR-Dijkstra

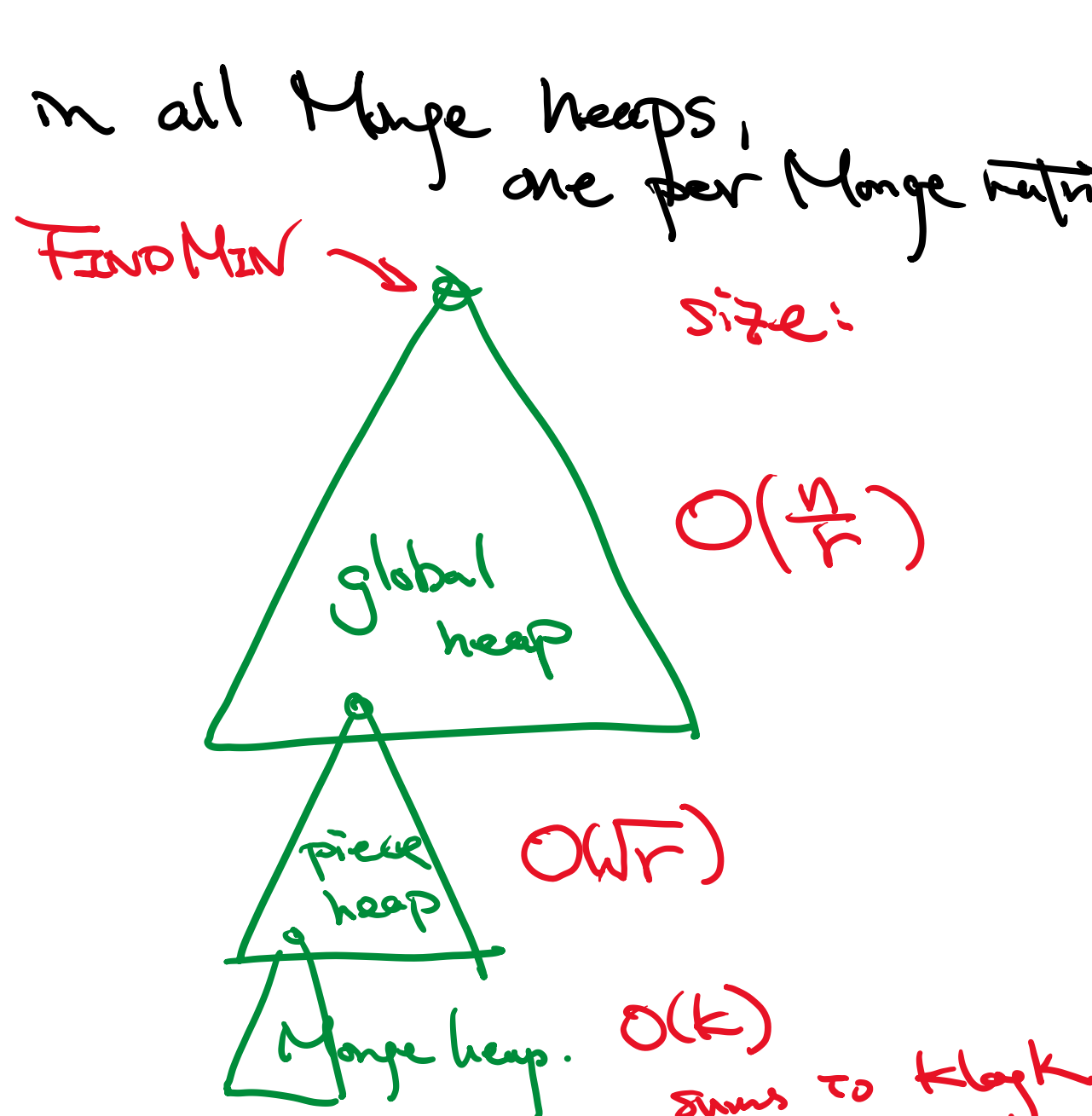
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In all Monge heaps relevant to s:
  REVEAL(s, 0)
  HIDE(s)

Repeat until t hidden:
  v ← FINDMIN()

In all Monge heaps relevant to v:
  REVEAL(v, dist(s,v))
  HIDE(v)

Return dist(t)
    
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Analysis of FR-Dijkstra:

- Each Monge heap takes $O(k \log k)$
 - All Monge heaps take $O(\frac{n}{r}) \cdot O(\sqrt{nr} \log r) \cdot O(k) = O(\frac{n}{r} \log^2 r)$
 - All piece heaps take $O(\frac{n}{r}) \cdot O(\log r) \cdot O(\log r)$
 - Global heap takes $O(\frac{n}{r}) \cdot O(\log n)$ (assuming $O(1)$ -deg)
- $O(\frac{n}{r} \log^2 n)$ in total.

$O(n)$ $+$ $O(n \log r)$ $+$ $O(\frac{n}{r} \log^2 n \cdot \log r)$ $+$ $O(\frac{n}{r} \cdot r \log r)$

Set $r = \log^2 n \Rightarrow O(n \log \log n)$ min cut.

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Technical Details ...

- r-division needs to respect strips.
- degenerate strips.
- Actually requires shortest paths to cut into strips.
- $O(1)$ -deg assumption.